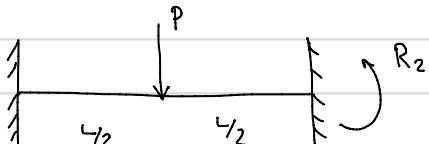


Fixed-end Forces / Moments

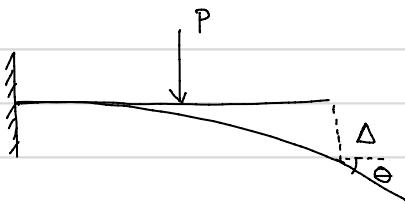


Indeterminate beam, use superposition!



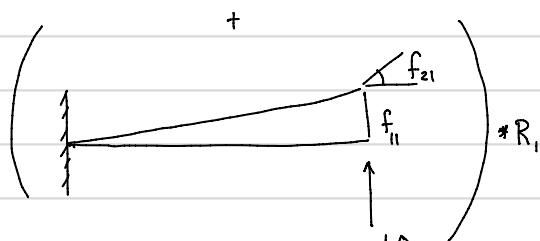
identify redundant reactions

=



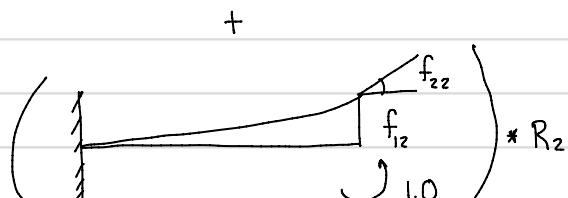
remove redundant reactions and apply loading

$$R_1 = R_2 = 0$$



$$R_1 = 1.0, R_2 = 0$$

$$\text{Note: } \Delta_1 = f_{11} R_1, \quad \Theta_1 = f_{21} R_1$$



$$R_2 = 1.0, R_1 = 0$$

$$\text{Note: } \Delta_2 = f_{12} R_2, \quad \Theta_2 = f_{22} R_2$$

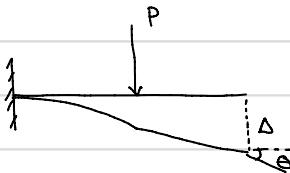
Compatibility

$$0 = \Delta + \Delta_1 + \Delta_2 \quad \text{displacement}$$

$$= \Delta + f_{11} R_1 + f_{12} R_2$$

$$0 = \Theta + \Theta_1 + \Theta_2 \quad \text{rotation}$$

$$= \Theta + f_{21} R_1 + f_{22} R_2$$



$$\Theta = -\frac{P(\gamma_2)^2}{2EI} = -\frac{PL^2}{8EI}$$

$$\Delta = -\frac{P(\gamma_2)^3}{3EI} + \Theta \cdot \gamma_2 = -\frac{5PL^3}{48EI}$$

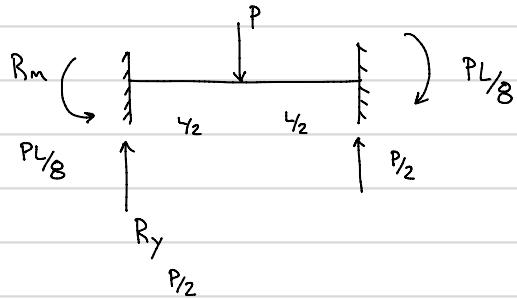
$$\begin{bmatrix} f_{11} & f_{12} \\ f_{21} & f_{22} \end{bmatrix} \begin{Bmatrix} R_1 \\ R_2 \end{Bmatrix} = \begin{Bmatrix} -\Delta \\ -\Theta \end{Bmatrix}$$

$$\begin{bmatrix} \frac{L^3}{3EI} & \frac{L^2}{2EI} \\ \frac{L^2}{2EI} & \frac{L}{EI} \end{bmatrix} \begin{Bmatrix} R_1 \\ R_2 \end{Bmatrix} = \begin{Bmatrix} \frac{5PL^3}{48EI} \\ \frac{PL^2}{8EI} \end{Bmatrix}$$

Solving system of equations yields

$$R_1 = \frac{P}{2} \quad \text{fixed-end-force (FEF)}$$

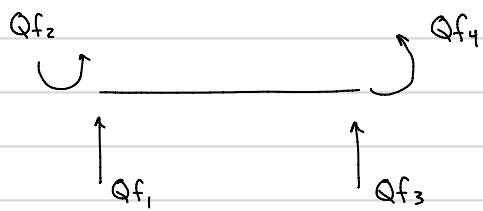
$$R_2 = -\frac{PL}{8} \quad \text{fixed-end-moment (FEM)}$$



From static equilibrium (determinate)

$$\sum F_y = 0 \quad R_y + \frac{P}{2} - P = 0 \quad R_y = \frac{P}{2}$$

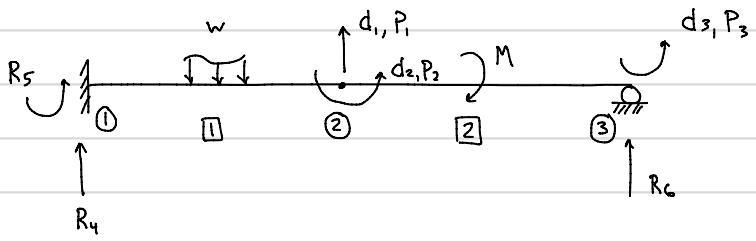
$$\sum M_b = 0 \quad R_m - P(L/2) + P/2(L) - PL/8 = 0$$



$$R_m = \frac{PL}{8}$$

$$\{Q_f\} = \left\{ \begin{array}{l} \frac{P}{2} \\ \frac{PL}{8} \\ \frac{P}{2} \\ -\frac{PL}{8} \end{array} \right\} \quad \text{use correct sign!}$$

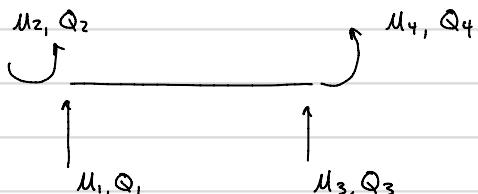
Assembly



1. Rigorous Method (joint equilibrium)

2. Code # Method

Code # number #	M_1, Q_1	M_2, Q_2	M_3, Q_3	M_4, Q_4
1	4	5	1	2
2	1	2	6	3



$$\{Q\} = \{Q_f\} + [k] \{M\}$$

$$1 \quad \begin{Bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{Bmatrix} = 4 \begin{Bmatrix} Q_{f1} \\ Q_{f2} \\ Q_{f3} \\ Q_{f4} \end{Bmatrix} + 5 \begin{Bmatrix} M_1, Q_1 \\ M_2, Q_2 \\ M_3, Q_3 \\ M_4, Q_4 \end{Bmatrix}$$

$$+ 5 \begin{bmatrix} k_{11} & k_{12} & k_{13} & k_{14} \\ k_{21} & k_{22} & k_{23} & k_{24} \\ k_{31} & k_{32} & k_{33} & k_{34} \\ k_{41} & k_{42} & k_{43} & k_{44} \end{bmatrix} \begin{Bmatrix} M_1 \\ M_2 \\ M_3 \\ M_4 \end{Bmatrix}$$

$$2 \quad \begin{Bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{Bmatrix} = 1 \begin{Bmatrix} Q_{f1} \\ Q_{f2} \end{Bmatrix} + 2 \begin{Bmatrix} Q_{f3} \\ Q_{f4} \end{Bmatrix} + 6 \begin{Bmatrix} M_1, Q_1 \\ M_2, Q_2 \\ M_3, Q_3 \\ M_4, Q_4 \end{Bmatrix}$$

$$+ 6 \begin{bmatrix} k_{11} & k_{12} \\ k_{21} & k_{22} \\ k_{31} & k_{32} \\ k_{41} & k_{42} \end{bmatrix} \begin{Bmatrix} M_1 \\ M_2 \\ M_3 \\ M_4 \end{Bmatrix}$$

$$\{P\} = \{P_f\} + [S]\{d\}$$

$$\begin{Bmatrix} P_1 \\ P_2 \\ P_3 \end{Bmatrix} = 1 \begin{Bmatrix} Q_{f_3}^1 + Q_{f_1}^2 \\ Q_{f_4}^1 + Q_{f_2}^2 \\ Q_{f_4}^2 \end{Bmatrix} + 2 \begin{Bmatrix} k_{33}^1 + k_{11}^2 & k_{34}^1 + k_{12}^2 & k_{14}^2 \\ k_{43}^1 + k_{21}^2 & k_{44}^1 + k_{22}^2 & k_{24}^2 \\ k_{41}^2 & k_{42}^2 & k_{44}^2 \end{Bmatrix} \begin{Bmatrix} d_1 \\ d_2 \\ d_3 \end{Bmatrix}$$

$$\{P - P_f\} = [S]\{d\}$$

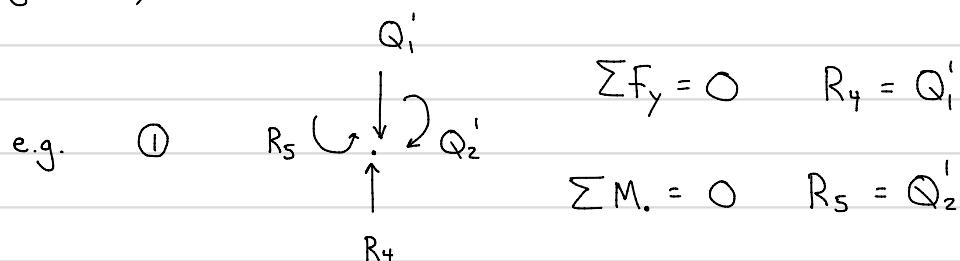
solve : $\{d\} = [S]^{-1} \{P - P_f\}$

post-process :

member-end forces $\{Q\} = \{Q_f\} + [k]\{\mu\}$

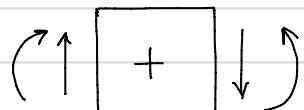
↓ compatibility w/ $\{d\}$

reactions joint equilibrium



shear and moment

diagrams



stresses

$$\sigma_b = -\frac{M_y}{I} \quad \tau = \frac{VQ}{Ib}$$